1701MF101	ADVANCED OPTIMIZATION TECHNIQUES	L	т	Р	С
		2	2	0	3

To introduce the various advanced optimization techniques and their advancements.

UNIT I INTRODUCTION

Optimization – Historical Development – Engineering applications of optimization – Statement of an Optimization problem – classification of optimization problems. Classical optimization Techniques – Linear Programming, Non-linear Programming, Integer Programming and Dynamic Programming.

UNIT II FUZZY SYSTEMS

Basic definition and terminology, set-theoretic operations, Fuzzy Sets, Operations on Fuzzy Sets, Fuzzy Relations, Membership Functions, Fuzzy Rules & Fuzzy Reasoning, Fuzzy Inference Systems, Fuzzy Expert Systems, Fuzzy Decision Making; Neuro-fuzzy modeling- Adaptive Neuro-Fuzzy Inference Systems, Coactive Neuro-Fuzzy Modeling, Classification and Regression Trees, Data Clustering Algorithms, Rulebase Structure Identification and Neuro-Fuzzy Control, Applications of neuro-fuzzy modeling

UNIT III ARTIFICIAL NEURAL NETWORKS

Introduction – Fundamental concept – Evolution of Neural Networks – Basic Models of Artificial Neural Networks – Important Terminologies of ANNs – McCulloch-Pitts Neuron – Linear Separability – Hebb Network. SupervisedLearning Network: Perceptron Networks – Adaline – Multiple Adaptive Linear Neurons – Back-Propagation Network – Radial BasisFunction Network. Applications of ANN.

UNIT IV GENETIC ALGORITHM

Introduction to Genetic Algorithms (GA), Representation, Operators in GA, Fitness function, population, building block hypothesis and schema theorem.; Genetic algorithms operators- methods of selection, crossover and mutation, simple GA(SGA), other types of GA, generation gap, steady state GA, Applications of GA

UNIT V SWARM INTELLIGENCE

Swarm intelligence, Various animal behaviors, Ant Colony optimization, swarm intelligence in bees, flocks of birds, shoals of fish, ant-based routing, Particle Swarm optimization

TOTAL: 45 HOURS

7 Hours

9 Hours

10 Hours

10 Hours

9 Hours

REFERENCES:

1.S.S. Rao, "Engineering Optimization: Theory and Practice", New Age International P)Ltd., New Delhi, 2000.

2.S. Rajasekaran and G.A.V.Pai, Neural Networks, Fuzzy Logic and Genetic Algorithms, PHI, 2003.

3. Timothy J.Ross, Fuzzy Logic with Engineering Applications, McGraw-Hill, 1997.

4.J.S.R.Jang, C.T.Sun and E.Mizutani, Neuro-Fuzzy and Soft Computing, PHI, 2004, Pearson Education.

5. S.N. Sivanandan and S.N. Deepa, Principles of Soft Computing, Wiley India, 2007. ISBN: 10: 81-265-1075-7

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1702MF102 POLYMERS AND COMPOSITE MATERIALS

COURSE OBJECTIVES:

- To study matrix material, reinforcements of polymer matrix composites, MMC and ceramic matrix composites.
- 2. To develop knowledge on processing, interfacial properties and application of composites.

UNITI	PROCESSING OF POLYMERS	9 Hours
Chemistry and	d Classification of Polymers - Properties of Thermo plastics - Properties of Thermosettii	ng Plastics
- Extrusion -	Injection Moulding - Blow Moulding - Compression and Transfer Moulding - Casting	 Thermo
Forming. Gen	eral Machining properties of Plastics - Machining Parameters and their effect - Joining	of Plastics
- Thermal bo	nding – Applications.	

UNIT II FIBERS AND MATRIX MATERIALS

DESCRIPTION OF BOX MANDO

Fibers – Fabrication, Structure, properties and applications – Glass fiber, Boron fiber, carbon fiber, organic fiber, ceramic and metallic fibers - whiskers–Fabrication of Matrix materials – polymers, metals and ceramics and their properties – interfaces – Wettability – Types of bonding at the interface– Tests for measuring interfacial strength - Physical and chemical properties.

UNIT III PROCESSING OF POLYMER MATRIX COMPOSITES 9 Hours

Thermoset matrix composites: hand layup, spray, filament winding, Pultrusion, resin transfer moulding, autoclave moulding - bag moulding, compression moulding with Bulk Moulding Compound and sheet Moulding Compound – thermoplastic matrix composites – film stacking, diaphragm forming, thermoplastic tape laying, injection moulding – interfaces in PMCs - structure, properties and application of PMCs –recycling ofPMCs.

UNIT IV PROCESSING OF METAL MATRIX COMPOSITES 9 Hours

Metallic matrices: aluminium, titanium, magnesium, copper alloys – processing of MMCs: liquid state, Solid state, in situ fabrication techniques – diffusion bonding – powder metallurgy techniques- interfaces in MMCs – mechanical properties – machining of MMCs – Applications.

UNIT V PROCESSING OF CERAMIC MATRIX COMPOSITES AND CARBON-CARBON COMPOSITES 9 Hours

Processing of CMCs: cold pressing, sintering, reaction bonding, liquid infiltration, lanxide process – in situ chemical reaction techniques: chemical vapour deposition, chemical vapour impregnation, sol-gel– interfaces in CMCs – mechanical properties and applications of CMCs – Carbon-carbon Composites –applications.

TOTAL: 45 HOURS

LTPC

0 0 3

....

9 Hours

3

REFERENCES:

 Krishnan K Chawla, Composite Materials: Science and Engineering, International Edition, Springer, 2012, ISBN:978-0-387-74364-6.

- Mallick P.K., Fiber Reinforced Composites: Materials, Manufacturing and Design, CRC press, New Delhi, 2010,ISBN:0849342058.
- Jamal Y. Sheikh-Ahmad, Machining of Polymer Composites, Springer, USA, 2009. ISBN: 978-0- 387-35539-9.
- 4. Mallick, P.K. and Newman.S., Composite Materials Technology, Hanser Publishers, 2003.
- 5. Harold Belofsky, Plastics, Product Design and Process Engineering, Hanser Publishers, 2002.
- 6. Seamour, E.B. Modern Plastics Technology, Prentice Hall, 2002
- Said Jahanmir, Ramulu M. and PhilpKoshy, Machining of Ceramics and Composites, Marcel Dekker Inc., New York, 1999, ISBN:0-8247-0178-x.
- 8. ASM Handbook Composites, Vol-21, 2001, ISBN: 978-0-87170-703-1.

1702MF103 MATERIALS TESTING AND MECHANICAL L Т C CHARACTERIZATION 3 0 0 3

COURSE OBJECTIVES:

The students are expected to be knowledgeable in microstructure evaluation, crystal structure analysis, electron microscopy, Chemical Thermal Analysis, static and dynamic mechanical testing methods.

UNIT I MICRO AND CRYSTAL STRUCTURE ANALYSIS

Principles of Optical Microscopy - Specimen Preparation Techniques - Polishing and Etching - Polarization Techniques - Quantitative Metallography - Estimation of grain size - ASTM grain size numbers -Microstructure of Engineering Materials - Elements of Crystallography - X- ray Diffraction - Bragg's law -Techniques of X-ray Crystallography - Debye - Scherer camera - Geiger Diffractometer - analysis of Diffraction patterns - Inter planer spacing - Identification of Crystal Structure, Elements of Electron Diffraction.

UNIT II ELECTRON MICROSCOPY

Interaction of Electron Beam with Materials - Transmission Electron Microscopy - Specimen Preparation -Imaging Techniques - BF & DF - SAD - Electron Probe Microanalysis - Scanning Electron Microscopy -Construction & working of SEM - various Imaging Techniques - Applications- Atomic Force Microscopy-Construction & working of AFM - Applications

UNIT III CHEMICAL ANDTHERMAL ANALYSIS

Basic Principles, Practice and Applications of X-Ray Spectrometry, Wave Dispersive X-Ray Spectrometry, Auger Spectroscopy, Secondary Ion Mass Spectroscopy, Fourier Transform Infra Red Spectroscopy (FTIR)-Proton Induced X-Ray Emission Spectroscopy, Differential Thermal Analysis, Differential Scanning Calorimetry (DSC) And Thermo Gravitymetric Analysis (TGA)

UNIT IV MECHANICAL TESTING -STATIC TESTS

Hardness - Brinell, Vickers, Rockwell and Micro Hardness Test - Tensile Test - Stress - Strain plot - Proof Stress - Torsion Test - Ductility Measurement - Impact Test - Charpy&Izod - DWTT - Fracture Toughness Test, Codes and standards for testing metallic and composite materials.

UNIT V MECHANICAL TESTING – DYNAMIC TESTS

Fatigue - Low & High Cycle Fatigues - Rotating Beam & Plate Bending HCF tests - S-N curve - LCF tests -Crack Growth studies - Creep Tests - LM parameters - AE Tests-modal analysis - Applications of Dynamic Tests.

REFERENCES:

1. Culity B.D., Stock S.R& Stock S., Elements of X ray Diffraction, (3rd Edition). Prentice Hall, 2001.

Dieter G.E., Mechanical Metallurgy, (3rdEdition), ISBN: 0070168938, McGraw Hill, 1988.

3. Davis, H.E., Hauck G. & Troxell G.E., The Testing of engineering Materials, (4th Edition), McGraw Hill, College Divn., 1982.

Suryanarayana A. V. K., Testing of metallic materials, (2ndEdition), BS publications, 2007.

5. Newby J., Metals Hand Book- Metallography & Micro Structures, (9th Edition), ASM International, 1989.

6. ASM Hand book-Materials characterization, Vol - 10,2004.

9 Hours

9 Hours

9 Hours

9 Hours

9 Hours

TOTAL: 45 HOURS

1702MF104	INDUSTRIAL AUTOMATION AND MECHATRONICS	L	Т	Р	С	
		3	0	0	3	

Knowledge in Industrial Automation and Mechatronics systems and impart the source of concepts and techniques, which have recently been applied in practical situation. It gives the frame work of knowledge that allows engineers and technicians to develop an interdisciplinary understanding and integrated approach to engineering

UNIT I INDUSTRIAL AUTOMATION

Role of automation in industries, Benefits of automation –Introduction to fluid power, Advantages of fluid power, Application of fluid power system -Types of fluid power systems -Introduction to automation tools: Low cost automation, PLC, DCS, SCADA -Automation strategy evolution.

UNIT II INTRODUCTION TO MECHATRONICS

Introduction to Mechatronics-systems – Mechatronics approach to modern engineering and design – Need of Mechatronics – Emerging areas of Mechatronics – Classification of Mechatronics – Mechatronics elements.

UNIT III SENSORS AND TRANSDUCERS

Introduction – Performance Terminology – Potentiometers – Strain gauges – LVDT – Eddy current sensor – Hall effect sensor – Capacitance sensors – Digital transducers – Temperature sensors – Optical sensors – Piezo electric sensor-ultrasonic sensors – Proximity sensors – Signal processing techniques.

UNIT IV ACTUATORS

Switching Devices, Classification of actuators – Electrical actuators – Solid state relays, solenoids, D.C. motors, Servo motors, Stepper motors – Interfacing with microcontroller through H-bridge Circuits – Piezoelectric actuators.

UNIT V MECHATRONIC SYSTEMS

Design process-stages of design process - Traditional and Mechatronics design concepts - Case studies -Engine management system, Automatic camera, Automatic wishing machine, Pick and place robots.

TOTAL: 45 HOURS

9 Hours

9 Hours

9 Hours

9 Hours

9 Hours

REFERENCES:

1.R.K.Rajput A Text Book of Mechatronics, Chand &Co,2007

2.W.Bolton,-Mechatronics/Pearson Education Limited,2004

3.M.A. Mazidi& J.G. Mazidi, 8051 Micrcontroller and embedded systems, 2002

4. Devadasshetty, Richard A. Kolk, -Mechatronics System Designl, PWS Publishing Company, 2001.

1702MF105	ROBOT DESIGN & PROGRAMMING	L	т	Р	С
		3	0	0	3

 To teach the students about the kinematic arrangement of robots and its applications in the area of manufacturing sectors

2. To expose the students to build a robot for any type of application

UNIT I INTRODUCTION

9 Hours

Definition, Need Application, Types of robots – Classifications – Configuration, work volume, control loops, controls and intelligence, specifications of robot, degrees of freedoms, end effectors – types, selection applications.

UNIT II ROBOT KINEMATICS 9 Hours Introduction – Matrix representation Homogeneous transformation, forward and inverse – Kinematic equations, Denvit – Hartenbers representations – Inverse Kinematic relations. Fundamental problems with D-H representation, differential motion and velocity of frames – Jacobian, Differential Charges between frames: UNIT III ROBOT DYNAMICS AND TRAJECTORY PLANNING 9 Hours Lagrangeon mechanics, dynamic equations for sing, double and multiple DOF robots – static force analysis of robots, Trajectory planning – joint space, Cartesian space description and trajectory planning – third order, fifth order - Polynomial trajectory planning 9 Hours UNIT IV ROBOT PROGRAMMING & AITECHNIQUES 9 Hours

Types of Programming - Teach Pendant programming - Basic concepts in A1 techniques - Concept of knowledge representations - Expert system and its components.

UNIT V ROBOT SENSORS AND ACTUATORS

Design of Robots – characteristics of actuating systems, comparison, microprocessors control of electric motors, magnetostrictive actuators, shape memory type metals, sensors, position, velocity, force, temperature, pressure sensors – Contact and non contact sensors, infrared sensors, RCC, vision sensors.

TOTAL: 45 HOURS

9 Hours

REFERENCES:

1. Saeed.B.Niku, Introduction to Robotics, Analysis, system, Applications', Pearson educations, 2002

2. Groover.M.P. Industrial Robotics, McGraw - Hill International edition, 1996.

 Wesley E Snyder R, Industrial Robots, Computer Interfacing and Control', Prentice Hall International Edition. 1988.

4. Gordon Mair, Industrial Robotics*, Prentice Hall (U.K.)1988

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1703MF003 MICRO ELECTRO MECHANICAL SXSTEMSAND, NANO L TPC TECHNOLOGY 3 0 03

AIM:

 To inspire the students to expect to the trends in manufacturing of micro components and measuring systems to nanoscale.

OBJECTIVES:

- To expose the students to the evolution of micro electromechanical systems, to the various fabrication techniques and to make students to be aware of microactuators.
- Also to impart knowledge to the students about papo materials and various papo measurements techniques.

UNITI OVER VIEW OF MEMSANDMICROSYSTEMS

Definition – historical development – properties, design and fabrication, micro-system, microelectronics, working principle, applications and advantages of micro system. Substrates and wafers, silicon as substrate material, mechanical properties of Si, Silicon Compounds - silicon piezo, resistors, Galium, arsenide, quartz, polymers for MEMS, conductive polymers.

UNITH FABRICATION PROCESSES AND MICROSYSTEM PACKAGING

Photolithography, photo resist applications, light sources, ion implantation, diffusion-Oxidation - thermal oxidation, silicon dioxide, chemical yapour deposition, sputtering - deposition by epitaxy - etching - bulk and surface machining - LIGA process - LASER, Electron beam Jon beam processes

 Mask less lithography. Micro system packaging – packaging design – levels of micro system packaging -die level, device level and system level – interfaces in packaging – packaging technologies. Assembly of Microsystems

UNITIII MICRODEVICES

Sensors - classification - signal conversion ideal characterization of sensors micro actuators, mechanical sensors - measurands - displacement sensors, pressure sensor, flow sensors, Accelerometer , chemical and bio sensor - sensitivity, reliability and response of micro-sensor - micro actuators - applications.

UNITIV SCIENCE AND SYNTHESIS OF NANOMATERIALS

Classification of pape structures - Effects of pape scale dimensions on various properties - structural, thermal, chemical, magnetic, optical and electronic properties fluid dynamics -Effect of pape, scale dimensions on mechanical properties - vibration, bending, fracture,

Nanoparticles, Sol-Gel Synthesis, Inert Gas Condensation, High energy Ball Milling, Plasma Synthesis, Electro deposition and other techniques. Synthesis of Carbon nanotubes – Solid carbon source based production techniques – Gaseous carbon source based production techniques – Diamond like carbon coating. <u>Top.down.and.</u> bottom.up.processes.

UNITY CHARACTERIZATION OFNANOMATERIALS

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10

10

Nano-processing systems – Nano measuring systems – characterization – analytical imaging techniques – microscopy techniques, electron microscopy scanning electron microscopy, confocal LASER scanning microscopy - transmission electron microscopy, transmission electron microscopy, scanning tunneling microscopy, atomic force microscopy, diffraction techniques – spectroscopy techniques – Raman spectroscopy, 3D surface analysis – Mechanical, Magnetic and thermal properties – Nano positioning systems.

TOTAL: 45 PERIODS

1704MF106	CAD / CAM LAB	L	т	Р	
		0	0	4	
COURSE OBJ					
1	. To teach the students about the drafting of 3D components and analyzing various CAD packages and programming of CNC machines	g the sar	ne usi	ing	
2	. To train them to use the various sensors				
LIST OF EXP	ERIMENTS:				1
CAM LABOR	ATORY				L
1. Exercise on C	'NC Lathe: Plain Turning				L
2. Exercise on C	'NC Milling Machine: Profile Milling				L
3. Study of Sens	ors				L
CAD LABOR/	ATORY				
2D modeling ar	d 3D modeling of components such as				L
1. Bearing					L
2. Couplings					L
3. Gears					L
4. Sheet Metal O	Components				L
5. Jigs. Fixtures	and Die Assemblies.				L
					L 1
		τοτλι	L: 45	ноц	R
		τοται	L: 45	HOU	R
		τοταί	L: 45	HOU	R
1704MF107		TOTAI	L: 45 T	HOU P	R
					R
	INDUSTRIAL AUTOMATION AND MECHATRONICS LAB			Р	R
1704MF107 COURSE OBJ	INDUSTRIAL AUTOMATION AND MECHATRONICS LAB	L 0	T O	P 2	R
1704MF107 COURSE OBJ	INDUSTRIAL AUTOMATION AND MECHATRONICS LAB ECTIVES: To train the students to have a hands on training of the basic concepts of v nutomation and Mechatronics systems	L 0	T O	P 2	R
1704MF107 COURSE OBJ LIST OF EXP	INDUSTRIAL AUTOMATION AND MECHATRONICS LAB ECTIVES: To train the students to have a hands on training of the basic concepts of v nutomation and Mechatronics systems	L 0	T O	P 2	R
1704MF107 COURSE OBJ LIST OF EXP 1. Simulation of	INDUSTRIAL AUTOMATION AND MECHATRONICS LAB ECTIVES: To train the students to have a hands on training of the basic concepts of v nutomation and Mechatronics systems ERIMENTS:	L 0	T O	P 2	R
1704MF107 COURSE OBJ LIST OF EXP 1. Simulation of 2. Simulation of	INDUSTRIAL AUTOMATION AND MECHATRONICS LAB ECTIVES: To train the students to have a hands on training of the basic concepts of v nutomation and Mechatronics systems ERIMENTS: 'single and double acting cylindercircuits	L 0	T O	P 2	R
1704MF107 COURSE OBJ LIST OF EXP 1. Simulation of 2. Simulation of 3. Simulation of	INDUSTRIAL AUTOMATION AND MECHATRONICS LAB ECTIVES: To train the students to have a hands on training of the basic concepts of v nutomation and Mechatronics systems ERIMENTS: 'single and double acting cylindercircuits 'Hydrauliccircuits	L 0	T O	P 2	R
1704MF107 COURSE OBJ LIST OF EXP 1. Simulation of 2. Simulation of 3. Simulation of	INDUSTRIAL AUTOMATION AND MECHATRONICS LAB ECTIVES: To train the students to have a hands on training of the basic concepts of v nutomation and Mechatronics systems ERIMENTS: 'single and double acting cylindercircuits 'Hydrauliccircuits 'electro pneumaticcircuits 'electro pneumaticcircuits	L 0	T O	P 2	R
1704MF107 COURSE OBJ LIST OF EXP 1. Simulation of 2. Simulation of 3. Simulation of 4. Simulation of 5. Simulation of	INDUSTRIAL AUTOMATION AND MECHATRONICS LAB ECTIVES: To train the students to have a hands on training of the basic concepts of v nutomation and Mechatronics systems ERIMENTS: 'single and double acting cylindercircuits 'Hydrauliccircuits 'electro pneumaticcircuits 'electro pneumaticcircuits	L 0	T O	P 2	R

TOTAL: 60 HOURS

1704MF108	COMMUNICATION SKILLS LAB I	L	т	P	C
	(Common to all M.E Progarmmes)	0	0	2	1

- 1. To acquire skills for using English in workplace effectively.
- 2. To communicate for essential business needs.
- 3. To prepare students for taking BEC Vantage level examination which is an International
- Benchmark for English language proficiency of Cambridge English Language Assessment

LIST OF EXPERIMENTS:

GRAMMAR AND VOCABULARY

Forming asking complex questions – expressing purpose and function –modal verbs – impersonal passive voice– Reported speech – cause and effect – relative pronouns – expressions followed by – *ing* forms– acronyms – marketing terms / vocabulary – financial terms – collocations – discourse markets

2. LISTENING

Purposes of listening – features of listening texts – potential barriers to listening – specific listening skills – strategies to use when listening– distinguishing relevant from irrelevant information – gap filling exercise – multiple-choice options – note completion – matching and multiple choice questions – listening for specific information, gist, topic, context and function.

3. SPEAKING

Word and sentence stress – clear individual sounds – turn taking – initiating and responding - intonation patterns – pronunciation – mother tongue intrusion– conversation practice – turn-taking and sustaining the interaction by initiating and responding appropriately- Public Speech – Lectures.

. READING

Purposes of reading – potential barriers to reading – paraphrasing – identifying facts and ideas – skimming and scanning for information – matching statements with texts– spotting reference words – understanding text structure – understanding the ideas in a text – distinguishing between the correct answer and the distracter – understanding cohesion in a text – deciphering contextual meaning of words and phrases – cloze – proof reading - transcoding.

S. WRITING

Paragraphing a text – using appropriate connectives – editing practice –Longer Documents: writing a proposal & Reports, Agenda – Minutes – Circular

ADDITIONAL EXPERIMENTS:

1. Body Language: Kinesics, Proxemics, Para linguistic, Nuances of Speech Delivery

TOTAL: 30 HOURS

- 2. Personality Development: Building self esteem
- 3. Team work

COURSE OUTCOMES:

- On the successful completion of the course, students will be able to
- CO1: To enable students to get International recognition for work and study.
- CO2: To use English confidently in the International business environments.
- CO3: To be able to take part in business discussion, read company literature, write formal and informal business correspondences and listen and understand business conversations

REFERENCES:

 Guy Brook-Hart, "BEC VANTAGE: BUSINESS BENCHMARK Upper-Intermediate – Student's Book", 1^{et} Edition, Cambridge University Press, New Delhi, 2006.

- Cambridge Examinations Publishing, "Cambridge BEC VANTAGE Self-study Edition", Cambridge University Press, UK, 2005.
- 3. Swets, Paul. W. 1983. The Art of Talking So That People Will Listen: Getting
- 4. The Process of Writing: Planning and Research, Writing, Drafting and Revising

	M.E. Manufacturing Engineering E.G.S. Pillay Engineering Approved in I Academic Council M				
1701MF201	ADVANCED MACHINING TECHNOLOGY	L	т	Р	C
		3	0	0	3
COURSE OBJE	CTIVES:				
	1. To impart knowledge in the area of advanced machining processes.				
UNIT I M	METAL CUTTING			8 H	ours
	echnology: Introduction to metal cutting - tool nomenclature and cu ting - tool materials - tool life and tool wear - traditional and nontradit				
UNIT II M	MECHANICAL ENERGY PROCESSES			10 H	ours
	esses: Ultrasonic Machining - Water Jet Machining - Abrasive Jet Mach ee Jet Machining - Magnetic Abrasive Finishing	ining - J	\brasi	ve W	ater
UNIT III 🔹 🤇	CHEMICAL ENERGY PROCESSES			9 H	ours
	etrochemical Processes: Chemical Milling - Photochemical Milling - E Machining - Electrochemical Drilling - Shaped Tube Electrolytic Machi		lishin	g -	
Thermal Processe	THERMAL ENERGY PROCESSES s: Electric Discharge Machining - Laser Beam Machining - Electron Be	sam Mac	hinin		ours
Plasma Beam Ma	chining - Ion Beam Machining				
	IYBRID PROCESSES				ours
	s: Electrochemical Grinding, Honing, Superfinishing and Buffing – Electroerosion Dissolution Machining - Abrasive Electrodischarge Mance				
		TOTA	L: 45	но	URS
COURSE OUTO	OMES: On the Successful completion of the course, Students will be able to				
	Select suitable machining process for suitable materials				
	Select optimum parameters for the respective machining process				
CO3: 5	Summarizes the merits and demerits of the non-traditional manufacturin	g proces	as i		
REFERENCES:					
1 Bhattacharva *	Metal Cutting Theory and Practice" New Central Book Agency (n) Ltd	Calcut	tta 198	4	

1. Bhattacharya "Metal Cutting Theory and Practice", New Central Book Agency (p) Ltd., Calcutta1984.

- Boothroy. D.G. and Knight. W.A "Fundamentals of Machining and Machine tools", Marcel Dekker, New York, 1989.
- 3. Hassan Abdel -- Gawad El-Hofy "Advanced Machining Processes", McGraw, New York, 2005.
- 4. Wellar, E.J. "Non-Traditional Machining Processes", Society of Manufacturing Engineers Publications, 2nd Edition, Michigan, 1984.
- 5. Metals Handbook. Vol. 16, Machining. Materials Park; OH: ASM International, 1995.
- 6. Kalpakjian, S "Manufacturing Process for Engineering Materials", MA:Addison-Wesley, 1997.
- Romyasjan, S. Halmatchang Process for Engineering Practicals , MC-Outloop Welley, 1997.
 Brown, J. "Advanced Machining Technology Handbook", New York: McGraw-Hill, 1998.
 McGeough, J. "Advanced Methods of Machining", London. New York: Chapman and Hall, London, 1988.
 Rumyantsev, E and Davydov, A "Electrochemical Machining of Metals", Moscow:Mir Publishers, 1984.

M.E. Manufacturing Engineering E.G.S. Pillay Engineering College Regulation	ns 2017
Approved in I Academic Council Meeting held on 16-	07-2017

1702MF202	FLEXIBLE TOOLING AND AUTOMATED INSPECTION	L	т	Р	С
		3	0	0	3
COURSE OBJE/	CTIVES:				

1. To impart knowledge in the area of Tooling in Manufacturing and Inspection.

UNIT I INTRODUCTION

Introduction to Principles of Tooling in Manufacturing-Economics of Tooling- Pre -Design Product and Process Analysis -Automated Tooling for Machining-Tool Changers-Tool Presets

UNIT II FLEXIBLETOOLING

Flexible Tooling –Tooling for Forming- Evolution of Dies, Forging, Bending and Drawing and Extrusion Processes- Tooling for Casting processes –Mechanization –Flexible tooling in Non Traditional Manufacturing

UNIT III MICRO-MANUFACTURING

Tooling for Micro Manufacturing-Tooling for Physical and Mechanical joining Processes-Tooling for CMM-Tool handling Robots.

UNIT IV VISUAL REALISM

Principles of Gauging - New concepts for gaging, inspection, checking, machine vision, and robotic testing. Smart Inspection Systems - Techniques and Applications of Intelligent Vision -Stages of automated visual inspection (AVI) and "smart" inspection systems- examples

UNIT V ARTIFICIAL INTELLIGENCE

Application of conventional and artificial intelligence techniques in AVI. AVI process, from illumination, image enhancement, segmentation and feature extraction, through to classification, and includes case studies of implemented AVI systems-Robots in Automated Inspection Tutorial: Design of Tooling Layout for Automats, Die Design, Modular Fixture Design Practice: Exercises in CMM and Robots for Inspection

TOTAL: 45 HOURS

9 Hours

9 Hours

9 Hours

9 Hours

9 Hours

On the Successful completion of the course, Students will be able to

- CO1: State of Art in Tooling in Manufacturing and Inspection
- CO2: Design and Develop tooling for Flexible Manufacturing
- CO3: Design and Develop Automated Inspection Systems

REFERENCES:

COURSE OUTCOMES:

 Mikell P Groover Fundamentals of Modern Manufacturing: Materials, Processes, and Systems John Wiley and Sons 2012.

- Stephen Murphy In-Process Measurement and Control: 32 (Series Manufacturing Engineering and Materials Processing) CRC Press 1990.
- Boothroyd, G. (2005). Assembly automation and product design (Vol. 536). Boca Raton, FL: Taylor & Francis.
- 4. Stanley L. Robinson, Richard Kendall Miller Automated Inspection and Quality Assurance 1989 CRC Press

 Duc T. Pham and R J Alcock Smart Inspection Systems: Techniques and Applications of Intelligent Vision Academic Press.

6. Black, J. Temple. The Design of the Factory with a Future. McGraw-Hill Companies, 1991.

.E.	Manufacturing	Engineering	EGS	. Pillay	Engineering	g College	Regulations 201	7
		Approve	ed in L	Academ	ie Council I	Meeting h	eld on 16-07-201	7

COURSE OBJECTIVES: 1. To study the basic concepts of metal forming techniques and to develop force calculation metal forming process. 2. To study the thermo mechanical regimes and its requirements of metal forming. UNIT I THEORY OF PLASTICITY 9H Theory of plastic deformation – Yield criteria – Tresca and Von-mises – Distortion energy – Stress- relation – Mohr, s circle representation of a state of stress – cylindrical and spherical co-ordinate system – wand lower bound solution methods – Overview of FEM applications in Metal Forming analysis. UNIT II THEORY AND PRACTICE OF BULK FORMING PROCESSES 8 H Analysis of plastic deformation in Forging, Rolling, Extrusion, rod/wire drawing and tube drawing – Effe friction – calculation of forces, work done – Process parameters, equipment used – Defeets – applicatio Recent advances in Forging, Rolling, Extrusion and Drawing processes – Design consideration in forming. UNIT II SHEET METAL FORMING 8 H Formability studies – Conventional processes – H E R F techniques – Superplastic forming techniques – H	2017				
1702MF203	THEORY OF METAL FORMING	L	т	Р	С
		3	0	0	3
COURSE OF	BJECTIVES:				
		p force	calcu	lation	in
	2. To study the thermo mechanical regimes and its requirements of metal	formin	g.		
UNIT I	THEORY OF PLASTICITY			9 H	ours
relation - Mo	hr,,s circle representation of a state of stress - cylindrical and spherical co-o	rdinate			
UNIT II	THEORY AND PRACTICE OF BULK FORMING PROCESSES			8 H	ours
					eis –
UNIT III	1702MF203 THEORY OF METAL FORMING L T P 3 0 0 COURSE OBJECTIVES: 1. To study the basic concepts of metal forming techniques and to develop force calculation metal forming process. 2. To study the thermo mechanical regimes and its requirements of metal forming. UNIT I THEORY OF PLASTICITY 91 Theory of plastic deformation – Yield criteria – Tresca and Von-mises – Distortion energy – Stress-relation – Mohr, s circle representation of a state of stress – cylindrical and spherical co-ordinate system – and lower bound solution methods – Overview of FEM applications in Metal Forming analysis. UNIT II THEORY AND PRACTICE OF BULK FORMING PROCESSES 8 H Analysis of plastic deformation in Forging, Rolling, Extrusion, rod/wire drawing and tube drawing – Eff friction – calculation of forces, work done – Process parameters, equipment used – Defects – applicati Recent advances in Forging, Rolling, Extrusion and Drawing processes – Design consideration in forming. UNIT III SHEET METAL FORMING 8 H	8 H	ours		

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Formability studies – Conventional processes – H E R F techniques – Superplastic forming techniques – Hydro forming – Stretch forming – Water hammer forming – Principles and process parameters – Advantage, Limitations and application

UNIT IV POWDER METALLURGY AND SPECIAL FORMING PROCESSES 9 Hours Overview of P/M technique – Advantages – applications – Powder preform forging – powder rolling – Tooling, process parameters and applications. - Orbital forging – Isothermal forging – Hot and cold isostatic pressing – High speed extrusion – Rubber pad forming – Fine blanking – LASER beam forming

UNIT V SURFACE TREATMENT AND METAL FORMING APPLICATIONS 9 Hours Experiment techniques of evaluation of friction in metal forming selection – influence of temperature and gliding velocity – Friction heat generation – Friction between metallic layers – Labrication carrier layer – Surface treatment for drawing, sheet metal forming, Extrusion, hot and cold forging. Processing of thin AI tapes – Cladding of AI alloys – Duplex and triplex steel rolling – Thermo mechanical regimes of Ti and AI alloys during deformation – Formability of welded blank sheet – Laser structured steel sheet - Formability of laminated sheet.

TOTAL: 45 HOURS

COURSE OUTCOMES:

On the Successful completion of the course, Students will be able to

- CO1: Fem applications in metal forming.
- CO2: Plastic deformations and recent advances in design.
- CO3: Powder metallurgy and metal forming applications.

REFERENCES:

- Helmi A Youssef, Hassan A. El-Hofy, Manufacturing Technology: Materials, Processes and Equipment, CRC publication press, 2012.
- 2. SAE Transactions, Journal of Materials and Manufacturing Section 5,1993-2007
- 3. Surenderkumar, Technology of Metal Forming Processes, Prentice Hall IndiaPublishers, 2010
- Marciniak Z., Duncan J.L., HuS. J., Mechanics of Sheet Metal Forming, Butterworth-Heinemann An Imprint of Elesevier, 2006.
- 5. Nagpal G.R., Metal Forming Processes- Khanna publishers, 2005
- 6. Altan T., Metal forming Fundamentals and applications American Society of Metals, Metals park, 2003
- ASM Hand book, Forming and Forging, Ninth edition, Vol 14,2003
 Shiro Kobayashi, Soo-IK-oh-Altan, T, Metal forming and Finite Element Method, Oxford University Press, 2001.
- Proc.OfNational Seminaron—Advances in Metal FormingIMIT, March2000
- Piecorioning Schularon Advances in Incluir Forming, Mill Classes
 Dieter G.E., Mechanical Metallurgy (Revised Edition II) McGraw Hill Co., 1988
- Altan, T, Soo-IK-oh, Gegel, HL Metal forming, fundamentals and Applications, American Society of Metals, Metals Park, Ohio, 1995.

	M.E. Manufacturing Engineering E.G.S. Pillay Engineering Approved in I Academic Council M				
1702MF204	ADVANCES IN CASTING AND WELDING	L	т	P	С
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COURSE OB.	2 0 URSE OBJECTIVES: 1. To study the metallurgical concepts and applications of casting and welding proces. 2. To acquire knowledge in CAD of casting and automation of welding process. TI CASTING DESIGN tt transfer between metal and mould — Design considerations in casting – Designing for diffication and minimum stresses - principles and design of gating andrisering TI I CASTING METALLURGY diffication of the metal-casting defects – Castability of steel , Cast Iron, Al alloys , Babbit alloy an IT III RECENT TRENDS IN CASTING AND FOUNDRY LAYOUT All moulding, precision investment casting, CO2 moulding, centrifugal casting, Die casting, ting, Counter gravity low pressure casting, Squeeze casting and semisolid processes. Layout of ndry – sand reclamation – material handling in foundry pollution control in foundry — Comign of castage. TI WELDING METALLURGY AND DESIGN tt affected Zone and its characteristics – Weldability of steels, cast iron, stainless steel, aluminum 				
	2. To acquire knowledge in CAD of casting and automation of welding p	rocess.			
	0.000.00000				
UNIT I					ours
		gning f	lor d	irecti	onal
UNIT II	CASTING METALLURGY			8 H	ours
UNIT III	RECENT TRENDS IN CASTING AND FOUNDRY LAYOUT			8 H	ours
Shell moulding	r, precision investment casting, CO2 moulding, centrifugal casting, Di	ie casti	ng, C	ontin	lous
	I reclamation - material handling in foundry pollution control in found				
UNIT IV	WELDING METALLURGY AND DESIGN			10 H	ours
Zirconium and Lamellar tearin	titanium alloys – Carbon Equivalent of Plain and alloy steels Hydro g – Residual stress – Distortion and its control . Heat transfer and solidi ded structures – pre and post welding heat treatments – weld joint design	gen en fication	nbrittle 1 - An	emen alysis	t – of
UNIT V	RECENT TRENDS IN WELDING			11 н	
Friction weldin welding - ultra	ag, friction stir welding – explosive welding – diffusion bonding – high sonic welding – electron beam welding – Laser beam welding –Plasma v w gap, hybrid twin wire active TIG – Tandem MIG- modern brazing and s	welding	ency i g – Ele	nduct	ion lag

induction, dip resistance, diffusion processes - Hot gas, wave and vapour plase soldering. Overview of automation of welding in aerospace, nuclear, surface transport vehicles and under waterwelding.

COURSE OUTCOMES:

- On the Successful completion of the course, Students will be able to
- CO1: Designing for directional solidification and minimum stresses.
- CO2: Solidification and cast ability of steel.
- CO3: Recent trends in welding.
- CO4: Analysis of stress in welded structures.
- CO5: Recent trends in casting technology.

REFERENCES:

1. ASM Handbook, Vol 15, Casting, 2004.

- ASM Handbook vol.6, welding Brazing & Soldering, 2003.
 Jain P.L., Principles of Foundry Technology, TataMcGrawHill Publishers, 2003.
- 4. Parmer R.S., Welding Engineering and Technology, KhannaPublishers, 2002.
- 5. Srinivasan N.K., Welding Technology, Khanna Tech Publishers, 2002
- 6. Heineloper& Rosenthal, Principles of Metal Casting, Tata McGraw Hill, 2000.
- Carry B., Modern Welding Technology, Prentice Hall Pvt Ltd., 2002.
 Cornu.J. Advanced welding systems Volumes I, II and III, JAICO Publishers, 1994.
- 9. Iotrowski, "Robotic welding-A guide to selection and application", Society of mechanical Engineers, 1987.
- Schwariz, M.M., "Source book on innovative welding processes", American Society for Metals (OHIO), 1981.
 Lancaster. J. F., "Metallurgy of welding", George Alien & Unwin Publishers, 1980.

TOTAL: 45 HOURS

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1702MF205	PRECISION MACHINING	L	т	Р	с
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COURSE OBJECTIVES:

1. To impart knowledge on various micro/nano finishing techniques for the production of required components.

UNIT I INTRODUCTION

Micro- manufacturing- types- micromachining- classification- mechanical advanced micro- machining processes.

UNIT II MEMS

Advanced nano finishing processes-Micro Electro Mechanical Systems (MEMS) - Nano Electro Mechanical Systems (NEMS).

UNIT III MICRO MACHING - 1

Lithography-diamond turning- micro drilling - micro milling - Electrical Discharge Micro-Machining (EDMM) Electro Chemical Micro-Machining (ECMM).

MICRO MACHING - 2 UNIT IV

Wire Electrical Discharge Micro-Machining (EDMM)- Laser Micro-Machining (LMM) - Types of Lasers Nano finishing- magnetorheological finishing process-micro/nano finishing with flexible flow of abrasives-Electrolytic In-process Dressing (ELID) Grinding.

ELECTRONMICROSCOPY UNIT V

Profilometers - optical microscopy - confocal laser scanning microscopy- Scanning Electron Microscope (SEM)-Atomic Force Microscope (AFM).

TOTAL: 45 HOURS

COURSE OUTCOMES:

On the Successful completion of the course, Students will be able to

- CO1: Recognize the various micro machining techniques.
- CO2: Apply various micro/nano finishing techniques for the production of required components
- CO3: State the metrological principles and techniques for the evaluation of precision machined components.

REFERENCES:

1. M.J. Madou, "Fundamentals of Micro Fabrication", CRC Press, 2002

2. V.K.Jain, "Introduction to Micromachining", Narosa Publishing House, 2010

3. Mark J. Jackson, "Micro Fabrication and Nano machining", Taylor and Francis, 2006

4. SeropeKalpakjian, "Manufacturing Engg. and Technology", Pearson Education, 2005

5. Yi Qin, "Micro-Manufacturing Engineering and Technology", Elsevier Publication, 2010

9 Hours

9 Hours

9 Hours

9 Hours

9 Hours

1703MF002 FLEXIBLE MANUFACTURING SYSTEMS COURSE OUTCOMES:

1. Define the flexibilities in FMS

2. Apply the components of FMS and their integration

3. Analyze the issues related to planning for successful implementation of FMS

UNITI INTRODUCTION

FMS Introduction and Description - Objectives and Benefits of FMS - Basic Components of FMS and their integration in the data processing systems - Types of FMS - FMS Layouts - Types of Flexibility - FMS design criteria- Group Technology - Cellular manufacturing - Differences between FMC and FMS

UNITH FMS WORKSTATIONS

FMS workstations - Machining station - CNC/DNC Features – Machine Tool applications - Machining Centers – Automated Features and Capabilities - Wash Stations - Coordinate Measuring Machines – Contact and noncontact inspection principles - Functions of CMM Computer/software

UNITHI INDUSTRIAL ROBOTS

Material Handling Systems - Introduction to material handling – material transport systems – AGV's conveyors – storage systems - AS/RS – Automatic data capture - Industrial Robots - Basic Configurations – Sensors in Robotics - robot cell design and control - Applications of Industrial Robots – Robot programming

UNITIV FMS SOFTWARE

FMS Software Structure, Functions and Description - General Structure and Requirements - Activities and Functions to be Performed by FMS Software - Requirements of FMS Software - Types of FMS Software Modules - Computer Simulation - Functions of an FMS Host Computer – Distributed systems in FMS – Part program preparation

UNITY CASE STUDIES

System Hardware and General Functionality - Programmable Logic Controllers - Cell Controllers -Communication Networks - FMS Installation and Implementation - Case Studies - Just-in-Time production – CIM Technology

TOTAL: 45 PERIODS

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COURSE OBJECTIVES:

· To train the students to have an hands on having the basic concepts of metal forming processes and to determine some metal forming parameters for a given shape.

METAL FORMING LAB

LIST OF EXI	ERIMENTS:
1. Determination	of strain hardening exponent.
2. Determination	of strain rate sensitivity index

Determination of strain rate sensitivity insex.
 Determination of straion test.
 Determination of efficiency in water hammer forming.
 Determination of interface friction factor.
 Study of rolling process.
 Determination of torque and force measurement in rolling mill.

TOTAL: 45 HOURS

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1704MF208	COMMUNICATION SKILLS LAB II	L	т	P	
	(Common to all M.E Progamimes)	0	0	2	1
COURSE OBJECTI	VES:				
	 To prepare students for taking BEC Vantage level examinati Cambridge English Language Assessment (CELA). To communicate appropriately in business contexts. To acquire skills for using English in business environment. 		ad by i	he	
LIST OF EXPERIM					
UNITI	SPEAKING	50.5			
making mini presenta	cation – agreeing / disagreeing, reaching decisions, giving and s tions – extending on conservations – collaborative task – tongue WRITING		pinice	15 -	
	- Shorter Documents: e-mail - memo - message - note - report	writing – fo	ormal	/ info	ema
		TOTAL	- 30	HOU	RS
COURSE OUTCOM					
CO	On the successful completion of the course, students will be 1: Enable students to acquire business terms for communication				
	 Enable students to acquire business terms for communication Use English confidently in the business contexts. 	JII.			
co		mal busines	s		

REFERENCES:

REPERENCES:
 I. Guy Brook-Hart, BEC VANTAGE: BUSINESS BENCHMARK Upper-Intermediate – Student's Book, 1st Edition, Cambridge University Press, New Delhi, 2006.
 Cambridge Examinations Publishing, Cambridge BEC VANTAGE – Self-study Edition, Cambridge University Press, UK, 2005.

FLUID POWER AUTOMATION

AIM:

To impart knowledge in the area of hydraulics, pneumatic and fluid power components and its functions.

OBJECTIVES:

- To make the students to learn the basic concepts of hydraulics and pneumatics and their controlling elements in the area of manufacturing process.
- To train the students in designing the hydraulics and pneumatic circuits using various design procedures.

UNIT I INTRODUCTION

Need for Automation, Hydraulic & Pneumatic Comparison – ISO symbols for fluid power elements, Hydraulic, pneumatics – Selection criteria.

UNIT II FLUID POWER GENERATING/UTILIZING ELEMENTS

Hydraulic pumps and motor gears, vane, piston pumps-motors-selection and specification-Drive characteristics – Linear actuator – Types, mounting details, cushioning – power packs – construction. Reservoir capacity, heat dissipation, accumulators – standard circuit symbols, circuit (flow) analysis.

symbols, circuit (flow) analysis

UNIT III CONTROL AND REGULATION ELEMENTS

Direction flow and pressure control valves-Methods of actuation, types, sizing of ports-pressure and temperature compensation, overlapped and underlapped spool valves-operating characteristics- electro hydraulic servo valves-Different types-characteristics and performance

UNIT IV CIRCUIT DESIGN

Typical industrial hydraulic circuits-Design methodology – Ladder diagram-cascade, method-truth table-Karnaugh map method-sequencing circuits-combinational and logic circuit.

UNIT V ELECTRO PNEUMATICS & ELECTRONIC CONTROL OF HYDRAULIC AND PNEUMATIC CIRCUITS

Electrical control of pneumatic and hydraulic circuits-use of relays, timers, counters, Ladder diagram. Programmable logic control of Hydraulics Pneumatics circuits, PLC ladder diagram for various circuits, motion controllers, use of field busses in circuits. Electronic drive circuits for various Motors.

REFERENCES:

- 1. W.Bolton, Mechatronics, Electronic control systems in Mechanical and Electrical Engineering Pearson Education, 2003.
- 2. Peter Rohner, Fluid Power Logic Circuit Design, Mcmelan Prem, 1994.
- **3**. Antony Esposito, Fluid Power Systems and control Prentice-Hall, 1988
- 4. E.C.Fitch and J.B.Suryaatmadyn. Introduction to fluid logic, McGraw Hill, 1978
- 5. Peter Rohner, Fluid Power logic circuit design. The Macmillan Press Ltd., London, 1979
- 6. Herbert R. Merritt, Hydraulic control systems, John Wiley & Sons, Newyork, 1967

Dudbey. A. Peace, Basic Fluid Power, Prentice Hall Inc, 1967.

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TOTAL: 45 PERIODS

AIM:

To stress the importance of NDT in engineering.

OBJECTIVES:

To introduce all types of NDT and their applications in Engineering.

UNIT I NON-DESTRUCTIVE TESTING: AN INTRODUCTION, VISUAL INSPECTION & LIQUID PENETRANT TESTING 6

Introduction to various non-destructive methods, Comparison of Destructive and Non destructive Tests, Visual Inspection, Optical aids used for visual inspection, Applications.

Physical principles, procedure for penetrant testing, Penetrant testing materials, Penetrant testing methods-water washable, Post – Emulsification methods, Applications

UNIT II EDDY CURRENT TESTING & ACOUSTIC EMISSION

Principles, Instrumentation for ECT, Absolute, differential probes, Techniques – High sensitivity techniques, Multi frequency, Phased array ECT, Applications.

Principle of AET, Instrumentation, Applications - testing of metal pressure vessels, Fatigue crack detection in aerospace structures.

UNIT III MAGNETIC PARTICLE TESTING & THERMOGRAPHY

Principle of MPT, procedure used for testing a component, Equipment used for MPT, Magnetizing techniques, Applications. Principle of Thermography, Infrared Radiometry, Active thermography measurements, Applications – Imaging entrapped water under an epoxy coating, Detection of carbon fiber contaminants.

UNIT IV ULTRASONIC TESTING

Principle, Ultrasonic transducers, Ultrasonic Flaw detection Equipment, Modes of display A- scan, B- Scan, C- Scan, Applications, Inspection Methods - Normal Incident Pulse-Echo Inspection, Normal Incident Through-transmission Testing, Angle Beam Pulse-Echo testing, TOFD Technique, Applications of Normal Beam Inspection in detecting fatigue cracks, Inclusions,Slag,Porosity

UNIT V RADIOGRAPHY

Principle of Radiography, x-ray and gamma ray sources- safety procedures and standards, Effect of radiation on Film, Radiographic imaging, Inspection Techniques – Single wall single image, Double wall Penetration, Multiwall Penetration technique, Real Time Radiography - Codes, standards, specification and procedures and case studies in Radiography test. Case studies on defects in cast, rolled, extruded, welded and heat treated components - Comparison and selection of various NDT techniques

TOTAL: 45 PERIODS

REFERENCES:

- 1. Baldev Raj, Jeyakumar, T., Thavasimuthu, M., -Practical Non Destructive Testing Narosa publishing house, New Delhi, 2002
- 2. Peter J. Shull -Non Destructive Evaluation: Theory, Techniques and Application Marcel Dekker, Inc., New York, 2002
- **3.** Krautkramer. J., -Ultra Sonic Testing of Materials, 1st Edition, Springer Verlag Publication, New York, 1996.
- 4. www.ndt.net

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AIM:

• To impart the knowledge and train the students in the area of metal cutting theory and its importance.

OBJECTIVES:

• To make the students familiar with the various principles of metal cutting, cutting tool materials and its wear mechanisms during the machining operation.

UNIT I INTRODUCTION

Need for rational approach to the problem of cutting materials-observation made in the cutting of metals-basic mechanism of chip formation-thin and thick zone modes-types of chips-chip breaker- orthogonal Vs oblique cutting-force velocity relationship for shear plane angle in orthogonal cutting- energy consideration in machining-review of Merchant, Lee and Shafter theories-critical comparison.

UNIT II SYSTEM OF TOOL NOMENCLATURE

Nomenclature of single point cutting tool-System of tool nomenclature and conversion of rake angles- nomenclature of multi point tools like drills, milling-conventional Vs climb milling, mean cross sectional area of chip in milling-specific cutting pressure.

UNIT III THERMAL ASPECTS OF MACHINING

Heat distribution in machining-effects of various parameters on temperature-methods of temperature measurement in machining-hot machining-cutting fluids.

UNIT IV TOOL MATERIALS, TOOL LIFE AND TOOL WEAR

Essential requirements of tool materials-development in tool materials-ISO specification for inserts and tool holders-tool life-conventional and accelerated tool life tests-concept of mach inability index- economics of machining.

UNIT V WEAR MECHANISMS AND CHATTER IN MACHINING

Processing and Machining – Measuring Techniques – Reasons for failure of cutting tools and forms of wear-mechanisms of wear-chatter in machining-factors effecting chatter in machining-types of chatter- mechanism of chatter.

TOTAL: 45 PERIODS

REFERENCES

- 1. Boothroid D.G. & Knight W.A., Fundamentals of machining and machine tools, Marcel Dekker, Newyork, 1989.
- 2. Shaw.M.C.Metal cutting principles, oxford Clare don press, 1984.
- 3. Bhattacharya.A., Metal Cutting Theory and practice, Central Book Publishers, India, 198

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